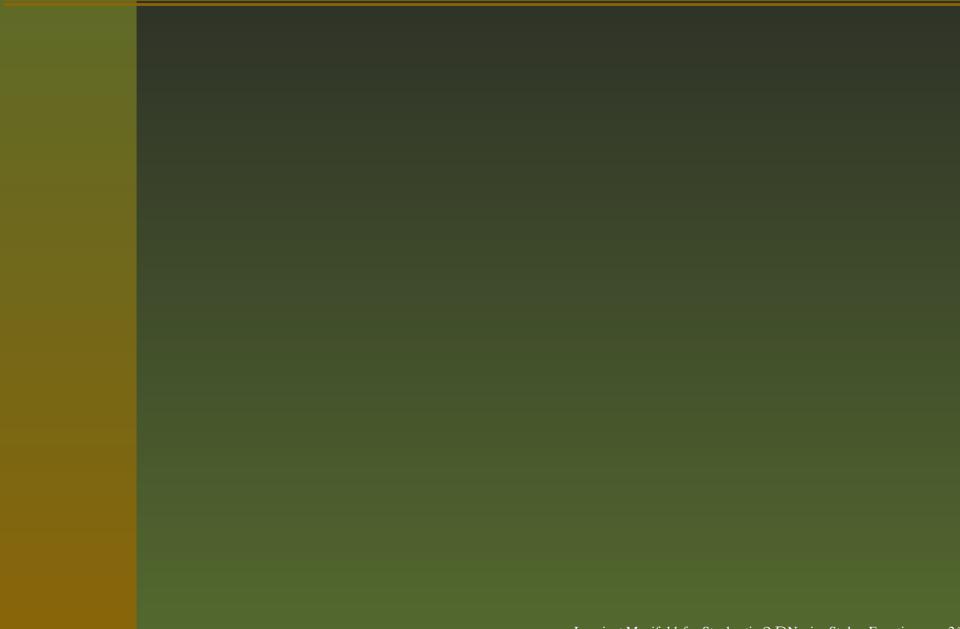
Invariant Manifolds for Stochastic 2D Navier-Stokes Equations

> Salah Mohammed ^{*a*} http://sfde.math.siu.edu/

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Joint work with Tusheng Zhang (Manchester, UK).

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The SNSE



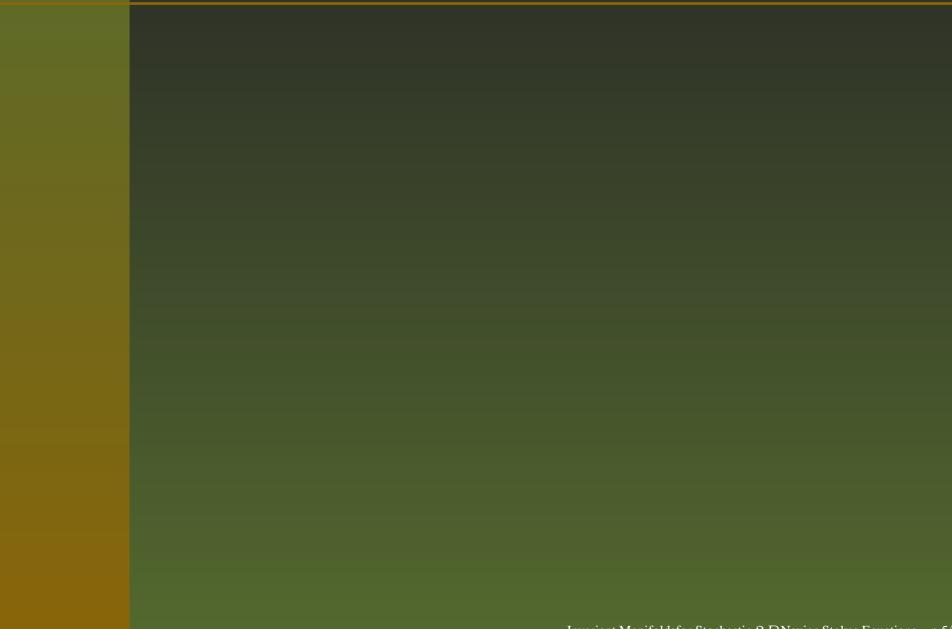
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 $du - \nu \Delta u \, dt + (u \cdot \nabla)u \, dt + \nabla p \, dt$ = $\gamma u \, dt + \sigma_0 \, dW_0(t, x) + \sum_{k=1}^{\infty} \sigma_k u(t) \, dW_k(t)$ $(\nabla \cdot u)(t, x) = 0, \quad x \in D, t > 0,$ $u(t, x) = 0, \quad x \in \partial D, t > 0,$ $u(0, x) = f(x), \quad x \in D.$



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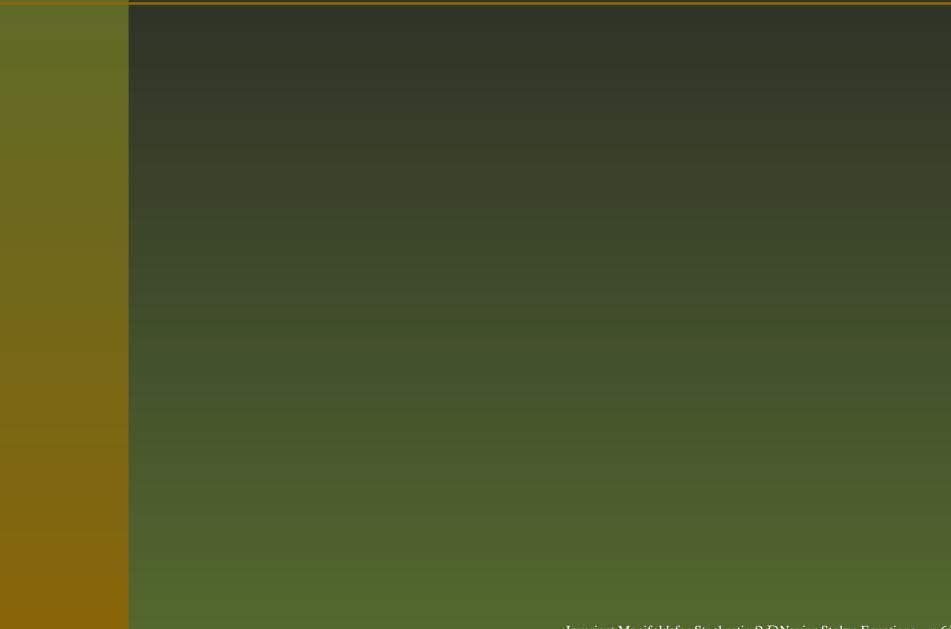
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 $W_k :=$ independent one-dimensional standard Brownian motions, $k \ge 1$, defined on a complete filtered Wiener space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \ge 0}, P)$;

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initial velocity $f: D \to \mathbf{R}^2$.



Perfection:

A family of propositions $\{P(\omega) : \omega \in \Omega\}$ holds perfectly in ω if there is a sure event $\Omega^* \in \mathcal{F}$ such that $\theta(t, \cdot)(\Omega^*) = \Omega^*$ for all $t \in \mathbf{R}$ and $P(\omega)$ is true for every $\omega \in \Omega^*$.

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Regularity:

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To establish:

- existence of a perfect locally compacting $C^{1,1}$ cocycle (semiflow) generated by all solutions of the stochastic Navier-Stokes equation;
- large-time asymptotics for the linearized stochastic semiflow on a stationary solution, given by a countable non-random Lyapunov spectrum of the cocycle;
- existence of flow-invariant C^1 local stable/unstable manifolds in the neighborhood of a hyperbolic stationary solution;



existence of a countable, flow-invariant C^1 local foliation through an ergodic stationary point (when $\gamma = 0$);

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- existence of a countable, global invariant flag relative to an ergodic stationary point (when $\gamma = 0$);
- sufficient conditions on the parameters ν, γ , $\sigma_i, i \ge 1$, (with $\sigma_0 = 0$) and the geometry of the domain *D* to guarantee uniqueness and hyperbolicity of the stationary solution (viz. the zero equilibrium).

The set-up



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Consider the Hilbert space

$$V := \{ v \in H_0^1(D, \mathbf{R}^2) : \nabla \cdot v = 0 \ a.e. \text{ in } D \},\$$

with the norm

$$||v||_{V} := \left(\int_{D} |\nabla v(x)|^{2} dx\right)^{\frac{1}{2}}$$

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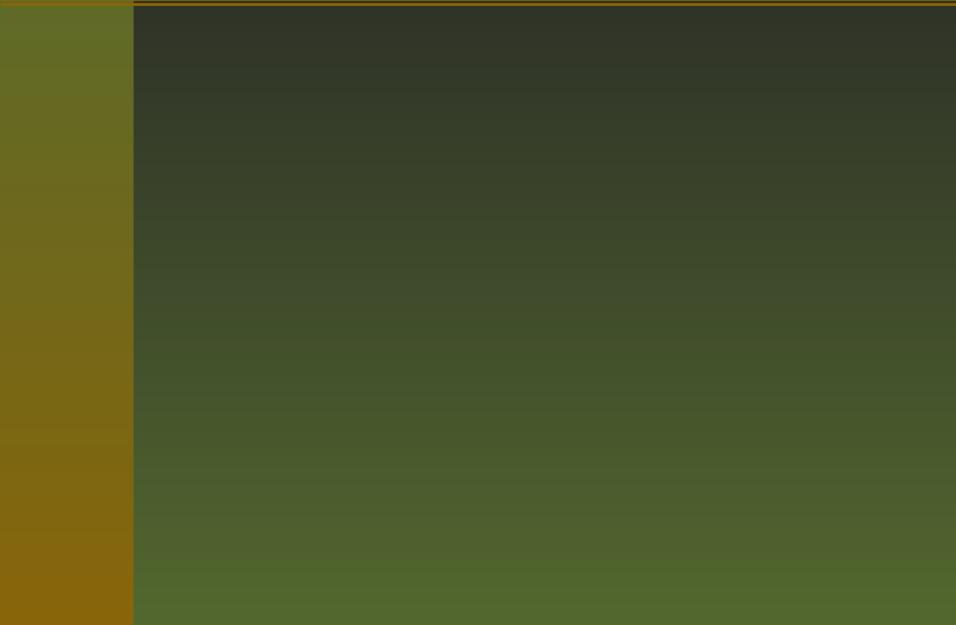
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and inner product $\ll \cdot, \cdot \gg$. $H := \text{closure of } V \text{ in the } L^2 \text{-norm}$

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Define the bilinear operator B by

 $B(u,v) := P_H((u \cdot \nabla)v),$

whenever u, v are such that $(u \cdot \nabla v)$ belongs to L^2 .

Short notation: B(u) := B(u, u).

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Apply the projection P_H to each term of the SNSE (1) and get abstract form:

du(t) + Au(t) dt + B(u(t)) dt $= \gamma u(t) dt + \sigma_0 dW_0(t) + \sum_{k=1}^{\infty} \sigma_k^H u(t) dW_k(t)$ $u(0) = f \in H$ (2)

in $L^2(0,T;V')$; V' := dual of V; $\sigma_k^H f := P_H(\sigma_k \circ f), f \in H.$

Existence of the Cocycle

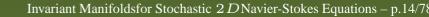
We show that strong solutions of the SNSE generate a Fréchet $C^{1,1}$ locally compacting cocycle (viz. stochastic semiflow) $u : \mathbb{R}^+ \times H \times \Omega \to H$ on the Hilbert space H.

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We show that strong solutions of the SNSE generate a Fréchet $C^{1,1}$ locally compacting cocycle (viz. stochastic semiflow) $u : \mathbf{R}^+ \times H \times \Omega \to H$ on the Hilbert space H.

Use a variational technique which transforms the SNSE into a *random* NSE. Then analyze the random NSE via a priori estimates coupled with lengthy estimates on Galerkin approximations. (cf. [Te], [Ro]).

Existence of the Cocycle-contd



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(3) For each $f \in H$, the SNSE (3) admits a unique strong solution

 $u(\cdot, f) \in L^2(\Omega; C([0, T]; H)) \cap L^2(\Omega \times [0, T]; V)$ ([B-C-F]). Invariant Manifoldsfor Stochastic 2*D* Navier-Stokes Equations – p.14/7

The Cocycle: Theorem

Let $u(t, f, \cdot)$ be the unique global solution of the SNSE (3) for $t \ge 0$ and $f \in H$. Denote by $\theta : \mathbb{R}^+ \times \Omega \to \Omega$ the standard Brownian shift

 $\theta(t,\omega)(s) := \omega(t+s) - \omega(t), \quad t,s \ge 0, \ \omega \in \Omega, \quad (4)$

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Then there is a version $u : \mathbb{R}^+ \times H \times \Omega \to H$ of the solution of (3) with the following properties:

The map $u : \mathbf{R}^+ \times H \times \Omega \to H$ is jointly measurable, and for each $f \in H$, the process $u(\cdot, f, \cdot) : \mathbf{R}^+ \times \Omega \to H$ is $(\mathcal{F}_t)_{t \ge 0}$ -adapted.

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$$(u, \theta)$$
 is a $C^{1,1}$ perfect cocycle; viz.

 $u(t_2, u(t_1, f, \omega), \theta(t_1, \omega)) = u(t_1 + t_2, f, \omega)$ (5) for all $t_1, t_2 \ge 0, f \in H, \omega \in \Omega$.

For each (t, f, ω) ∈ R⁺ × H × Ω, the Fréchet derivative Du(t, f, ω) ∈ L(H) of the map u(t, ·, ω) is compact linear, and the map

$$\mathbf{R}^{+} \times H \times \Omega \longrightarrow L(H)$$
$$(t, f, \omega) \longmapsto Du(t, f, \omega)$$

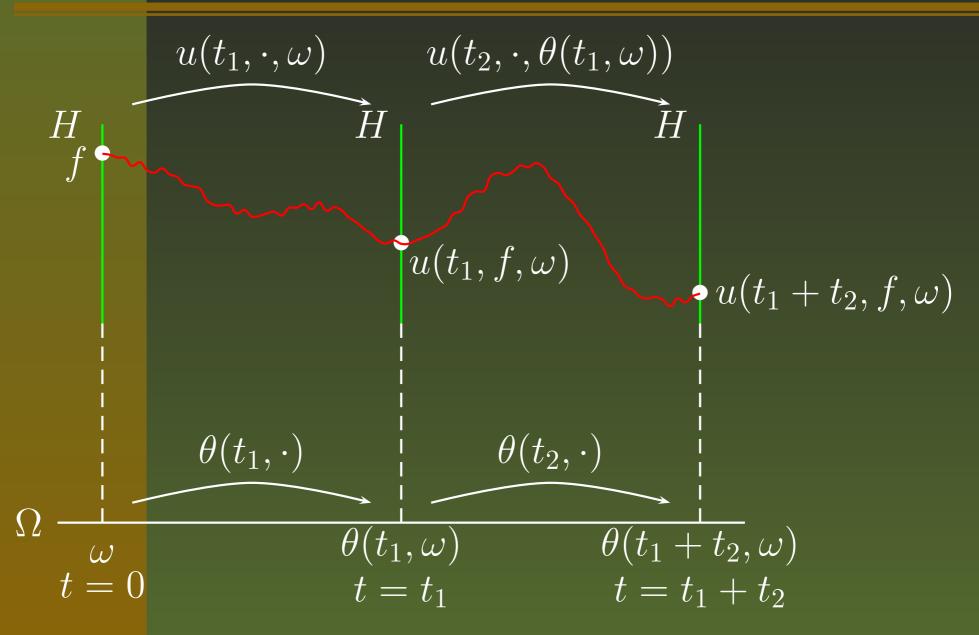
is strongly measurable.

For fixed $\rho, a > 0$,

 $E \log^{+} \sup_{\substack{0 \le t_1, t_2 \le a \\ |f|_H \le \rho}} \left\{ |u(t_2, f, \theta(t_1, \cdot))|_H \right\}$

 $+ \|Du(t_2, f, \theta(t_1, \cdot))\|_{L(H)} \} < \infty.$ (6)

The cocycle property





Define $u: \mathbf{R}^+ \times H \times \Omega \to H$ by setting

 $u(t, f, \omega) := Q(t, \omega)[v(t, f, \omega) + Z(t, \omega)], \qquad (7)$

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 $Q(t) = I + \gamma \int_0^t Q(s) \, ds + \sum_{k=1}^\infty \int_0^t \sigma_k Q(s) \, dW_k(s), \, t \ge 0$

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 $Q(t) = I + \gamma \int_{0}^{t} Q(s) \, ds + \sum_{k=1}^{\infty} \int_{0}^{t} \sigma_{k} Q(s) \, dW_{k}(s), \ t \ge 0$ (8) $Z(t) := \sigma_{0} \int_{0}^{t} Q(s)^{-1} T_{t-s} \, dW_{0}(s), \quad t \ge 0;$

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dv(t) = -Av(t) dt- Q(t)B(Q(t)(v(t) + Z(t)), v(t) + Z(t)) dt, $v(0) = f \in H.$

(9`

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Existence of a unique global solution to the random NSE (9) follows by Galerkin approximations, a priori estimates and compactness of the embedding $V \rightarrow H$. Obtain Lipschitz and Fréchet differentiability ($C^{1,1}$) properties for v and hence for u using very lengthy estimates on v and its Gateaux derivatives.

(9)



To show the perfect cocycle property for u, observe that Q has the cocycle property

 $Q(t_1 + t_2, \omega) = Q(t_2, \theta(t_1, \omega))Q(t_1, \omega), \ t_1, t_2 \ge 0, \ \omega \in \Omega.$ (10)

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 $Q(t_1+t_2,\omega) = Q(t_2,\theta(t_1,\omega))Q(t_1,\omega), t_1,t_2 \ge 0, \ \omega \in \overline{\Omega}.$ The cocycle property for u will follow from the identity $Q(t_1,\omega)[v(t_1+t_2,f,\omega)+T_{t_2}Z(t_1,\omega)]$ $= v(t_2, Q(t_1, \omega)[v(t_1, f, \omega) + Z(t_1, \omega)], \theta(t_1, \omega))$ for $t_1, t_2 \ge 0, \omega \in \Omega, f \in H$. Above identity holds by uniqueness of the solution to the random NSE (9).

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 $\begin{aligned} &|u(t_{2}, f, \theta(t_{1}, \omega))|_{H} \\ &= Q(t_{2}, \theta(t_{1}, \omega))v(t_{2}, f, \theta(t_{1}, \omega)) + Z(t_{2}, \theta(t_{1}, \omega))|_{H} \\ &\leq Q(t_{2}, \theta(t_{1}, \omega)[|f|_{H} + c(\omega)] \\ &\leq [\rho + c(\omega)] ||Q||_{\infty} ||Q^{-1}||_{\infty}, \end{aligned}$ (12) where $||Q^{-1}||_{\infty} := \sup_{0 \leq t \leq 2a} ||Q^{-1}(t)||$ and $E \log c < \infty.$

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 $|u(t_2, f, \theta(t_1, \omega))|_H$ $= Q(t_2, \theta(t_1, \omega) | v(t_2, f, \theta(t_1, \omega)) + Z(t_2, \theta(t_1, \omega))|_H$ $\leq Q(t_2, \theta(t_1, \omega)[|f|_H + c(\omega)])$ $\leq [\rho + c(\omega)] ||Q||_{\infty} ||Q^{-1}||_{\infty},$ where $||Q^{-1}||_{\infty} := \sup_{0 \le t \le 2a} ||Q^{-1}(t)||$ and $E \log c < \infty$. Using a priori estimates on Dv, we obtain

$\|Du(t_{2}, f, \theta(t_{1}, \omega))\|_{L(H)}$ = $Q(t_{2}, \theta(t_{1}, \omega)\|Dv(t_{2}, f, \theta(t_{1}, \omega))\|_{L(H)}$ $\leq c_{1}(\omega)\|Q\|_{\infty}\|Q^{-1}\|_{\infty}\exp\{c_{2}(\omega)|f|_{H}^{2}\}$ (13)

where

 $E \log c_1 < \infty, \quad E c_2 < \infty.$

The above two estimates imply

 ∞ .

 $E \log^+ \sup |u(t_2, f, \theta(t_1, \cdot))|_H$ $0 \le t_1, t_2 \le a$ $|f|_H \leq \rho$ $+ E \log^{+} \sup_{0 \le t_{1}, t_{2} \le a} \| Du(t_{2}, f, \theta(t_{1}, \cdot)) \|_{L(H)}$ $|f|_H \leq \rho$ (14)

That is:

$$E \log^{+} \sup_{0 \le t_1, t_2 \le a} \| u(t_2, \cdot, \theta(t_1, \cdot)) \|_{C^1} < \infty$$

where $\|\cdot\|_{C^1}$ denotes the C^1 norm on the closed ball $B(0,\rho)$ in H, center 0 and radius ρ .

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is a stationary random point or equilibrium for the cocycle (u, θ) if

 $u(t, Y(\omega), \omega) = Y(\theta(t, \omega))$

for all $t \in \mathbf{R}^+$, and $\omega \in \Omega$.



Let $Y : \Omega \to H$ be a stationary random point for the cocycle (u, θ) of SNSE (3) with $E \log^+ |Y| < \infty$.

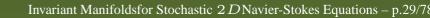
Let $Y : \Omega \to H$ be a stationary random point for the cocycle (u, θ) of SNSE (3) with $E \log^+ |Y| < \infty$. Then $(Du(t, Y(\omega), \omega), \theta(t, \omega))$ is a compact linear cocycle.

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 $\Lambda(\omega) := \lim_{t \to \infty} \left\{ \left[Du(t, Y(\omega), \omega) \right]^* \circ \left[Du(t, Y(\omega), \omega) \right] \right\}^{1/2t}$

Limit exists in the uniform operator norm in L(H) perfectly in $\omega \in \Omega$ -(Ruelle-Oseledec theorem). [Ru]

Lyapunov exponents-contd



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The Oseledec-Ruelle operator is compact, self-adjoint and non-negative with fixed discrete spectrum

 $e^{\lambda_1} > e^{\lambda_2} > e^{\lambda_3} > \cdots > e^{\lambda_n} > \cdots$

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The Lyapunov exponents

$$\{\cdots < \lambda_{i+1} < \lambda_i < \cdots < \lambda_2 < \lambda_1\}$$

are values of the almost sure limit

 $\lim_{t \to \infty} \frac{1}{t} \log |Du(t, Y(\omega), \omega)(g)|_H, \ g \in H.$

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"Dynamically": expect ergodicity to be a non-generic property; but hyperbolicity is generic.

Next result gives necessary and sufficient conditions for hyperbolicity of the zero equilibrium $Y \equiv 0$.



In SNSE (3), the zero equilibrium is hyperbolic if and only if the following conditions hold

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Proof: Use the formula

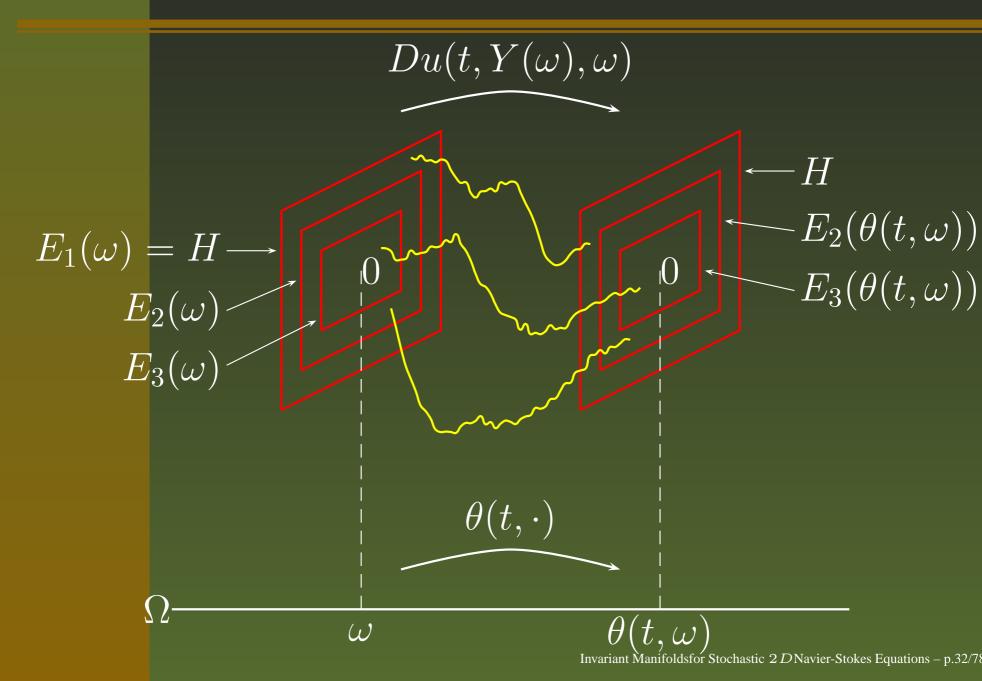
$$\lambda_n = \gamma - \mu_n - \frac{1}{2} \sum_{k=1}^{\infty} |\sigma_k|^2, \ n \ge 1$$

for the Lyapunov exponents of the linearized cocycle $(Du(t, 0, \omega), \theta(t, \omega)).$

Linearization: Spectral theorem



Linearization: Spectral theorem



 $\{\mathcal{U}(\omega), \mathcal{S}(\omega) : \omega \in \Omega\}$:= unstable and stable subspaces associated with the linearized cocycle $(Du(t, Y(\omega), \omega), \theta(t, \omega))$ ([Mo.3], [M.S]). $\begin{array}{l} \{\mathcal{U}(\omega), \mathcal{S}(\omega) : \omega \in \Omega\} := \text{unstable and stable subspaces} \\ \text{associated with the linearized cocycle} \\ (Du(t, Y(\omega), \omega), \theta(t, \omega)) \ ([\text{Mo.3}], [\text{M.S}] \). \end{array} \end{array}$ Then get a measurable perfect invariant splitting

 $H = \mathcal{U}(\omega) \oplus \mathcal{S}(\omega),$

 $Du(t, Y(\omega), \omega)(\mathcal{U}(\omega)) = \mathcal{U}(\theta(t, \omega)),$ $Du(t, Y(\omega), \omega)(\mathcal{S}(\omega)) \subseteq \mathcal{S}(\theta(t, \omega)),$

for all $t \ge 0$.

Random saddles-Contd

Have exponential dichotomies:

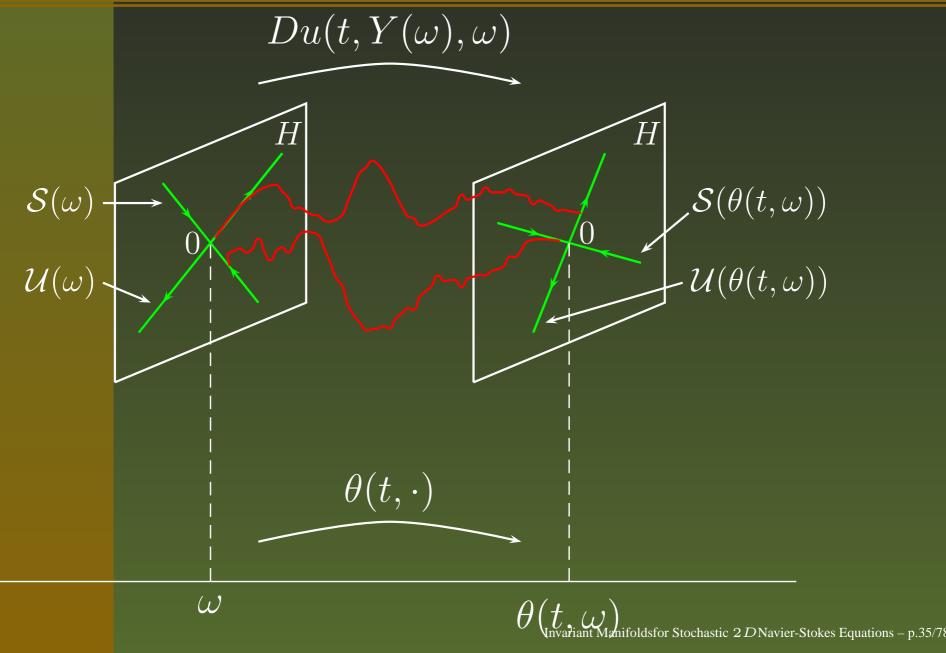
 $|Du(t, Y(\omega), \omega)(x)| \ge |x|e^{\delta_1 t}$
for all $t \ge 0, x \in \mathcal{U}(\omega)$;

 $|Du(t, Y(\omega), \omega)(x)| \le |x|e^{-\delta_2 t}$

for all $t \ge 0, x \in \mathcal{S}(\omega)$, and $\delta_i > 0$, fixed, i = 1, 2.

Random saddles-contd

 Ω



The stable manifold theorem



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Let $Y : \Omega \to H$ be a hyperbolic stationary random point for the cocycle (u, θ) of the SNSE (3) with $E \log^+ |Y| < \infty$.

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The stable manifold theorem

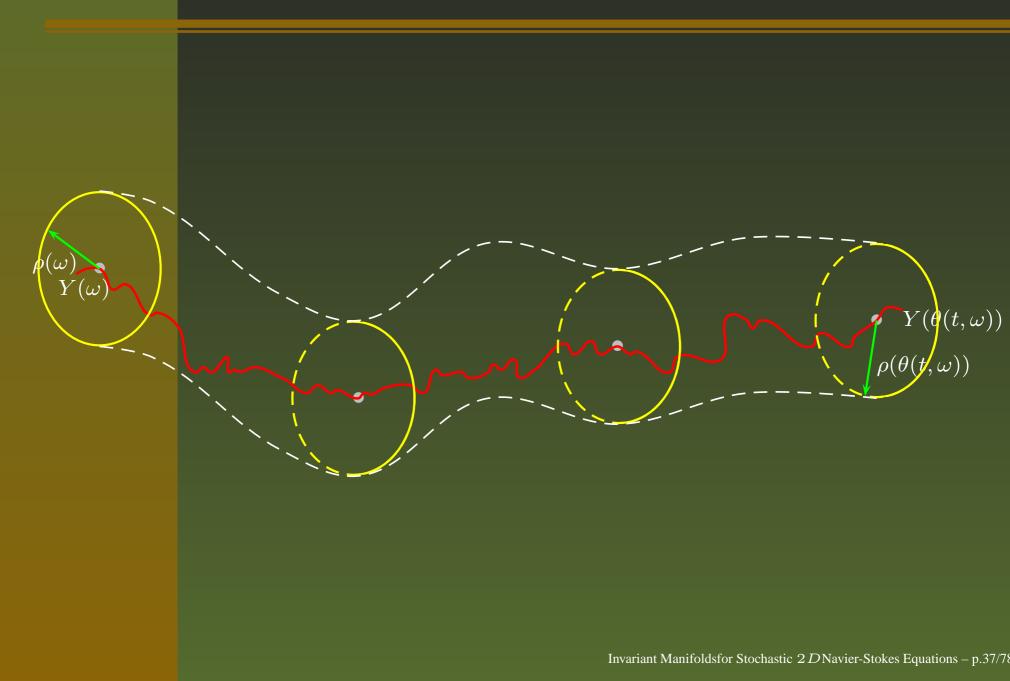
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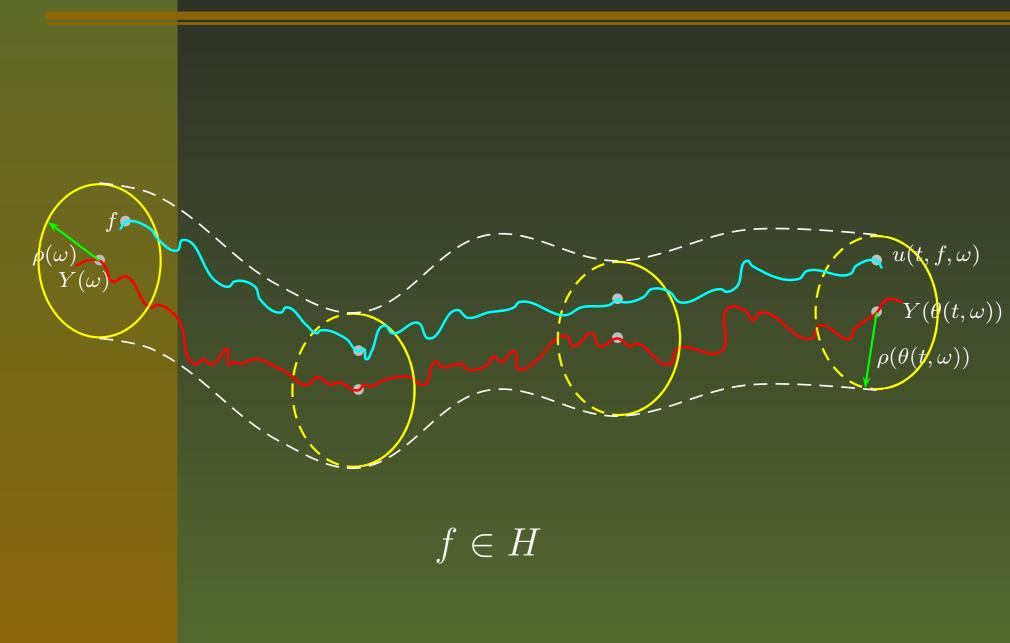
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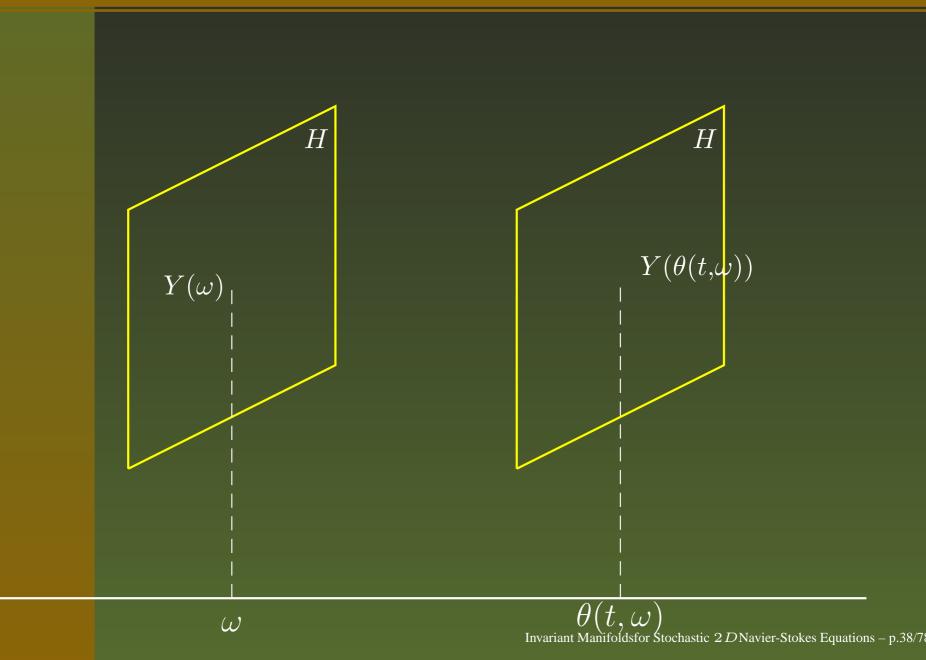
First, we view a stationary tube around the hyperbolic equilibrium Y.



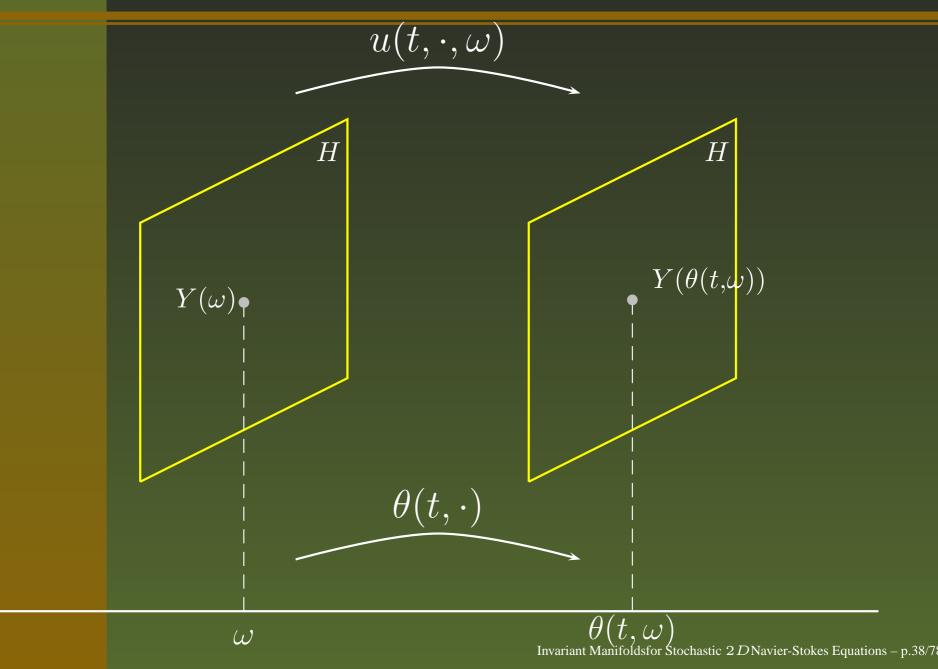


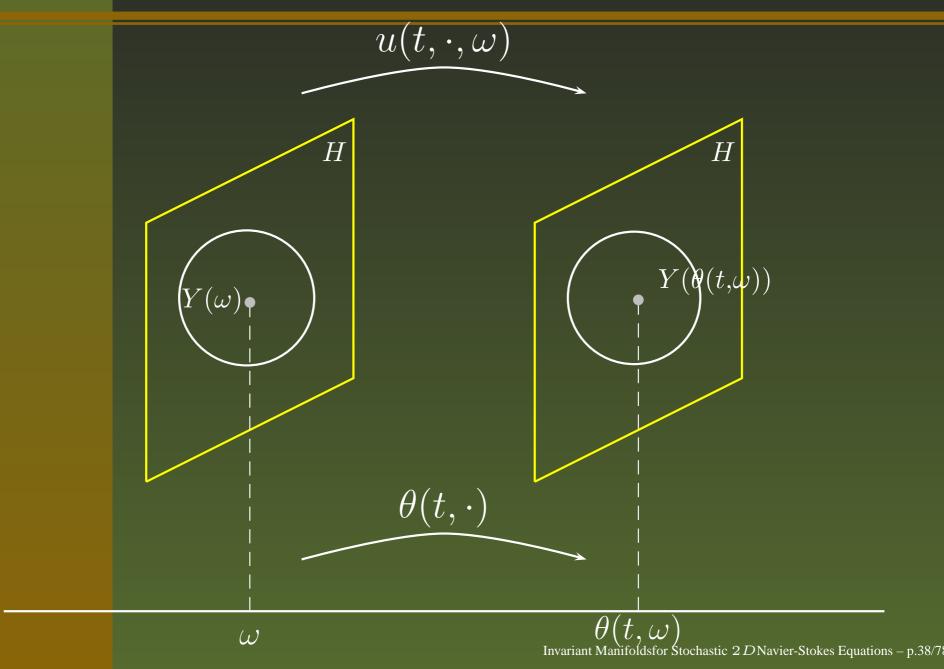


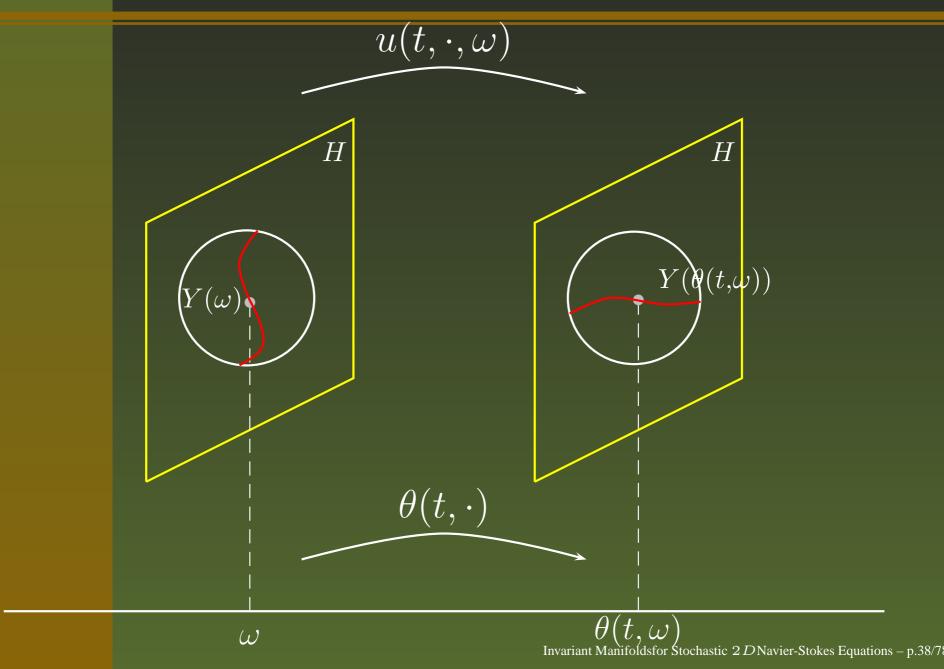


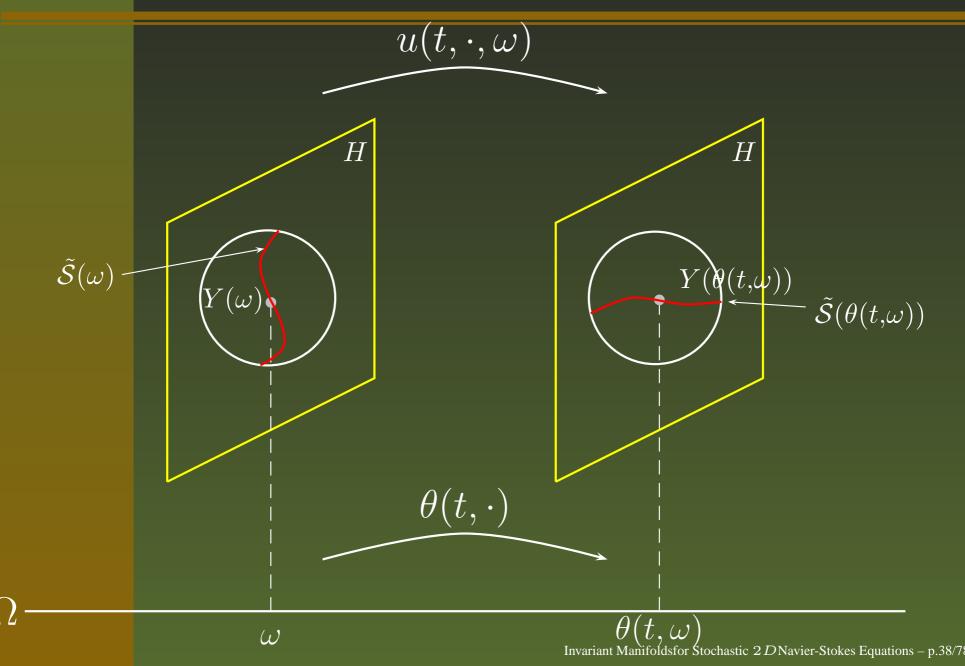


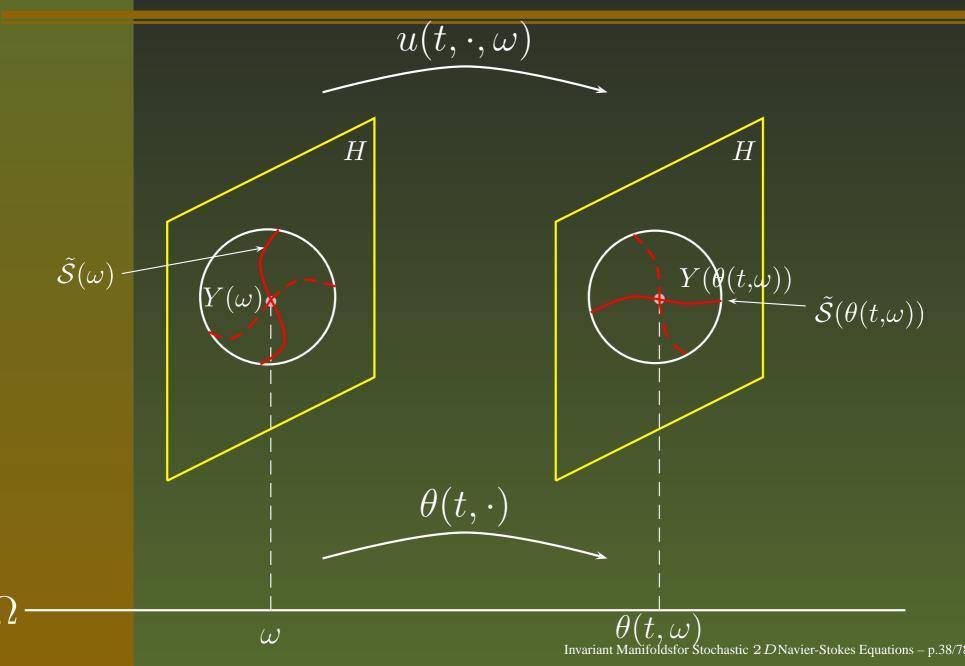
 S_{2}

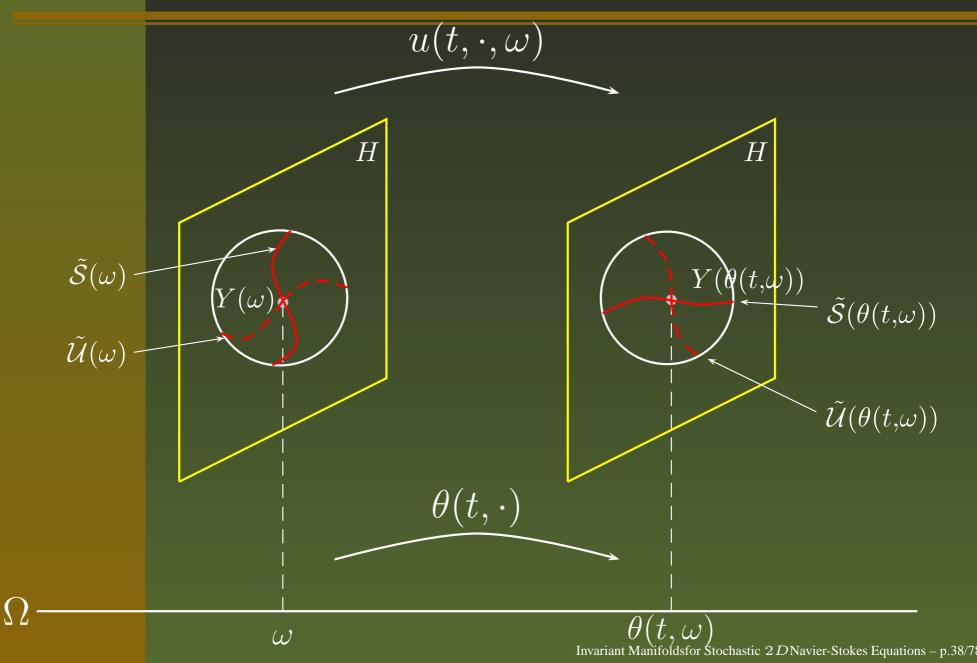


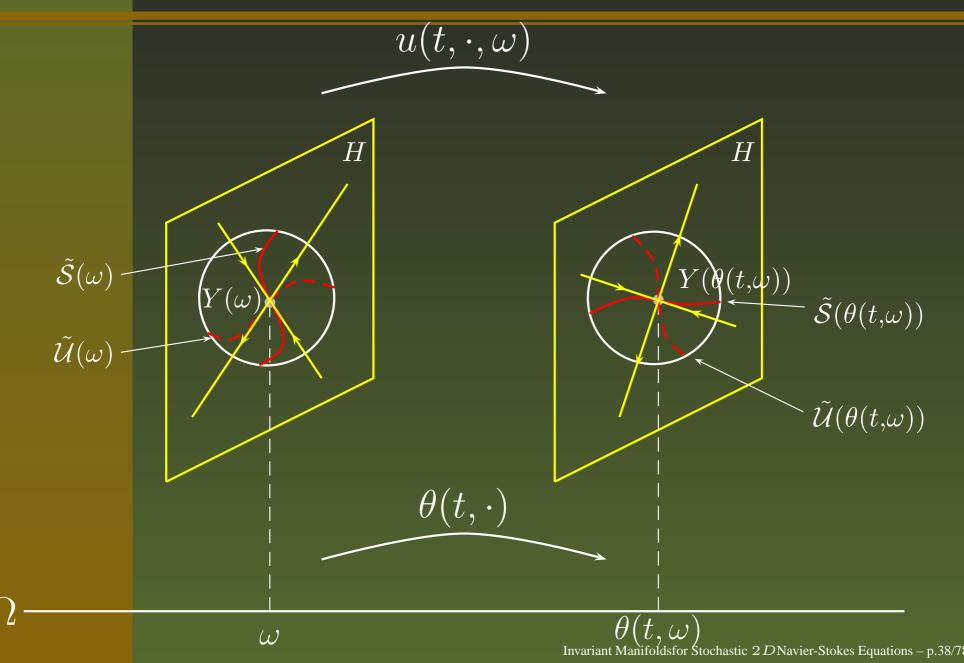


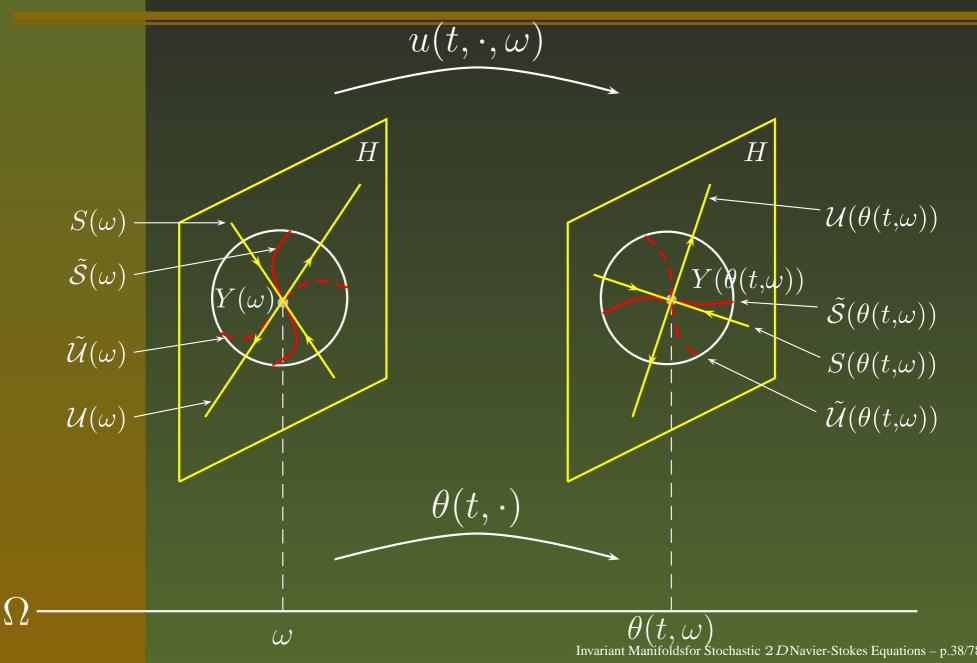


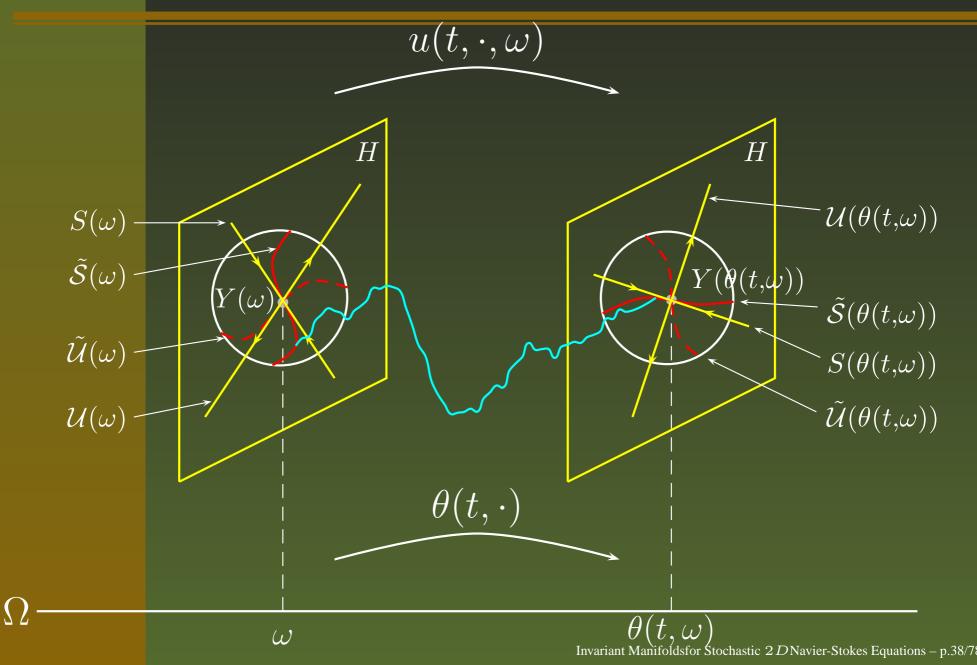


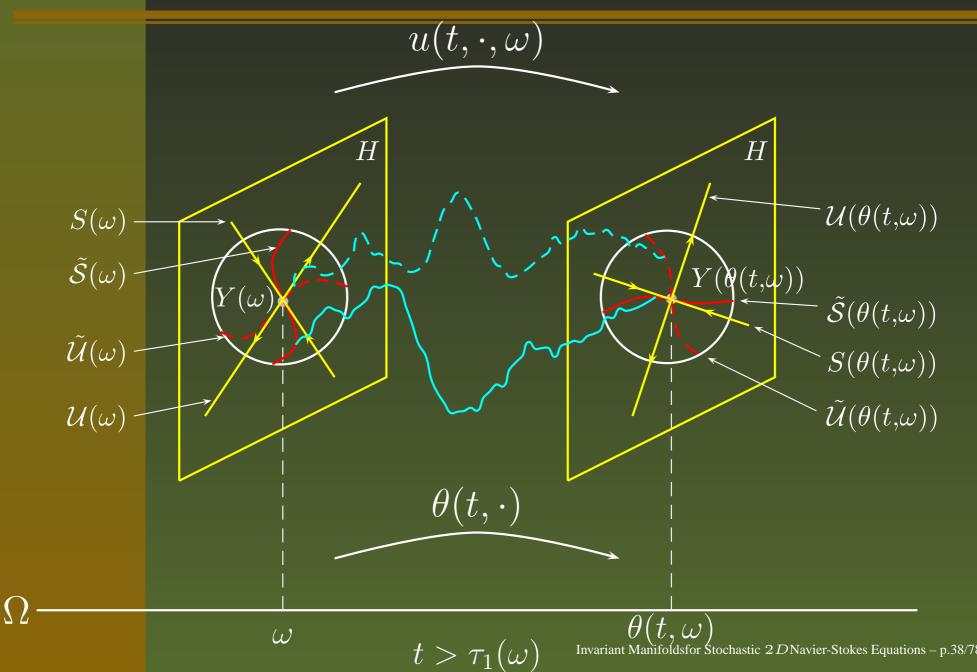














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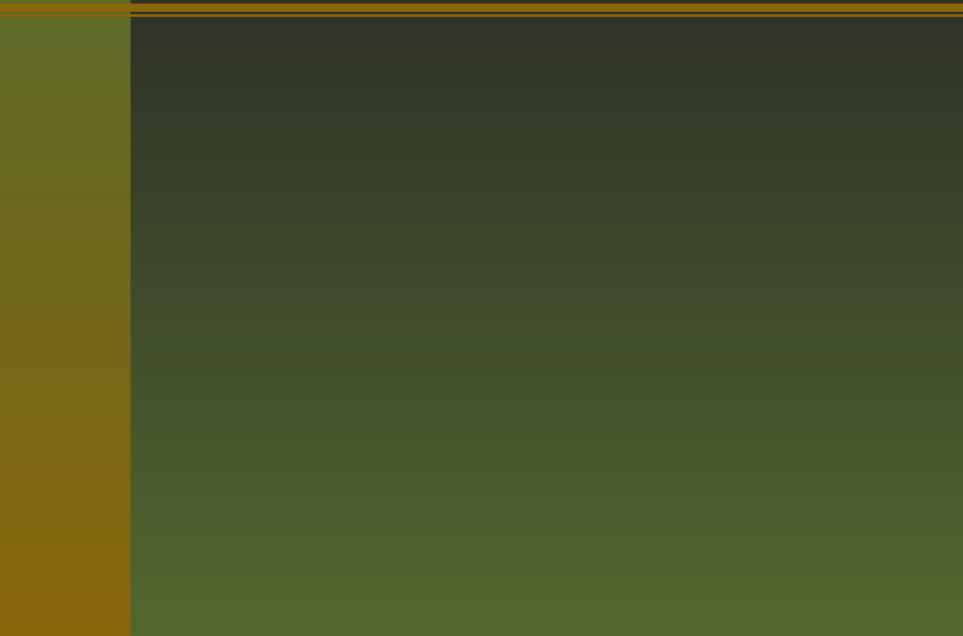
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- The Local Invariant Manifold Theorem
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The local invariant manifold theorem characterizes the almost sure asymptotic stability of the random flow of the SNSE (3) in the neighborhood of an ergodic stationary point Y.

The global invariant foliation theorem gives random cocycle-invariant foliations in H, characterized by the Lyapunov exponents at an ergodic stationary point Y.



Let (u, θ) be the cocycle generated by the SNSE (3) with $\gamma = 0$. Suppose Y is an ergodic stationary point of (3) with a Lyapunov spectrum $\{\lambda_i : i \ge 1\}$ and $\lambda_1 < 0$. Fix $\epsilon \in (0, -\lambda_1)$. Then there exist

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(i) a sure event $\Omega^* \in \mathcal{F}$ with $\theta(t, \cdot)(\Omega^*) = \Omega^*$ for all $t \in \mathbf{R}$,

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- (i) a sure event $\Omega^* \in \mathcal{F}$ with $\theta(t, \cdot)(\Omega^*) = \Omega^*$ for all $t \in \mathbf{R}$,
- (ii) \mathcal{F} -measurable random variables $\rho_i, \beta_i : \Omega^* \to (0, 1), \ \beta_i > \rho_i \ge \rho_{i+1} > 0, \ i \ge 1$, such that for each $\omega \in \Omega^*$, the following is true:



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For each $i \geq 1$, there is a C^1 submanifold $\tilde{\mathcal{S}}_i(\omega)$ of $B(Y(\omega), \rho_i(\omega))$ with the following properties: (a) $\tilde{\mathcal{S}}_i(\omega)$ is the set of all $f \in B(Y(\omega), \rho_i(\omega))$ such that $|u(n, f, \omega) - Y(\theta(n, \omega))|_H \le \beta_i(\omega) \exp\{(\lambda_i + \epsilon)n\}$ for all integers n > 0. Furthermore, for each $f \in \tilde{\mathcal{S}}_i(\omega)$: $\limsup_{t \to \infty} \frac{1}{t} \log |u(t, f, \omega) - Y(\theta(t, \omega))|_H \le \lambda_i$

Invariant Manifoldsfor Stochastic 2DNavier-Stokes Equations – p.41/78



Each $\tilde{S}_{i+1}(\omega)$ is a submanifold of $\tilde{S}_i(\omega)$; and $T_{Y(\omega)}\tilde{S}_i(\omega) = E_i(\omega)$. In particular, $\operatorname{codim} \tilde{S}_i(\omega) = \operatorname{codim} E_i(\omega)$ (fixed and finite).

Each $\tilde{\mathcal{S}}_{i+1}(\omega)$ is a submanifold of $\tilde{\mathcal{S}}_i(\omega)$; and $T_{Y(\omega)}\tilde{\mathcal{S}}_i(\omega) = E_i(\omega)$. In particular, $\operatorname{codim} \tilde{\mathcal{S}}_i(\omega) = \operatorname{codim} E_i(\omega)$ (fixed and finite). (b) $\limsup_{t \to \infty} \frac{1}{t} \log \left[\sup \left\{ \frac{|u(t, f_1, \omega) - u(t, f_2, \omega)|_H}{|f_1 - f_2|_H} : \right\} \right]$ $f_1 \neq f_2, f_1, f_2 \in \tilde{\mathcal{S}}_i(\omega) \bigg\} \bigg] \leq \lambda_i$



(c) (Cocycle-invariance): There exist $\tau_i(\omega) \ge 0$ such that

$$u(t,\cdot,\omega)(\tilde{\mathcal{S}}_i(\omega)) \subseteq \tilde{\mathcal{S}}_i(\theta(t,\omega))$$

for all $t \geq \tau_i(\omega)$.

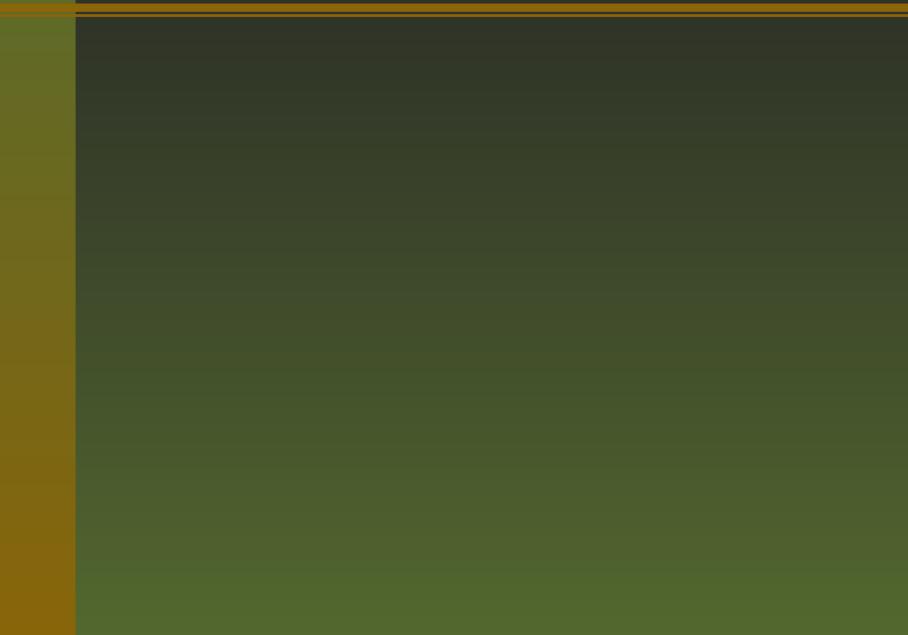
Invariant manifolds-contd

(c) (Cocycle-invariance): There exist $\tau_i(\omega) \ge 0$ such that

 $u(t,\cdot,\omega)(\tilde{\mathcal{S}}_i(\omega)) \subseteq \tilde{\mathcal{S}}_i(\theta(t,\omega))$

for all $t \geq \tau_i(\omega)$. Also

 $Du(t, Y(\omega), \omega)(E_i(\omega)) \subseteq E_i(\theta(t, \omega)), \quad t \ge 0.$



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Define the random sets $M_i(\omega), \ \omega \in \Omega^*, \ i \ge 1$, by

$$\begin{split} M_i(\omega) \\ &:= \left\{ f \in H : \overline{\lim_{t \to \infty} \frac{1}{t}} \log |u(t, f, \omega) - Y(\theta(t, \omega))|_H \le \lambda_i \right\} \\ &\text{for } i \ge 1, \omega \in \Omega^*. \end{split}$$

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for $i \geq 1, \omega \in \Omega^*$.

For fixed $i \ge 1, \omega \in \Omega^*$, define the sequence $\{S_i^n(\omega)\}_{n=1}^{\infty}$, inductively by:

$$\begin{split} S_i^1(\omega) &:= \tilde{\mathcal{S}}_i(\omega) \\ S_i^n(\omega) &:= \begin{cases} u(n, \cdot, \omega)^{-1} \big[\tilde{\mathcal{S}}_i \big(\theta(n, \omega) \big) \big], \\ & \text{if } S_i^{n-1}(\omega) \subseteq u(n, \cdot, \omega)^{-1} \big[\tilde{\mathcal{S}}_i \big(\theta(n, \omega) \big) \big] \\ S_i^{n-1}(\omega), & \text{otherwise,} \end{cases} \end{split}$$

for all $n \ge 2$, where $\tilde{\mathcal{S}}_i(\omega), i \ge 1$, are the local invariant C^1 manifolds at $Y(\omega)$.

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for all $n \ge 2$, where $\tilde{\mathcal{S}}_i(\omega), i \ge 1$, are the local invariant C^1 manifolds at $Y(\omega)$.

Then the following is true for each $i \ge 1$ and $\omega \in \Omega^*$:



(i) Each $M_i(\omega)$ is cocycle- invariant:

$$u(t,\cdot,\omega)(M_i(\omega)) \subseteq M_i(\theta(t,\omega))$$

for all $t \ge 0$.

(i) Each $M_i(\omega)$ is cocycle- invariant: $u(t, \cdot, \omega) (M_i(\omega)) \subseteq M_i(\theta(t, \omega))$ for all $t \ge 0$. (ii) $S_i^n(\omega) \subseteq S_i^{n+1}(\omega)$ for all $n \ge 1$, and $M_i(\omega) = \bigcup S_i^n(\omega)$ n = 1

(perfectly in ω).



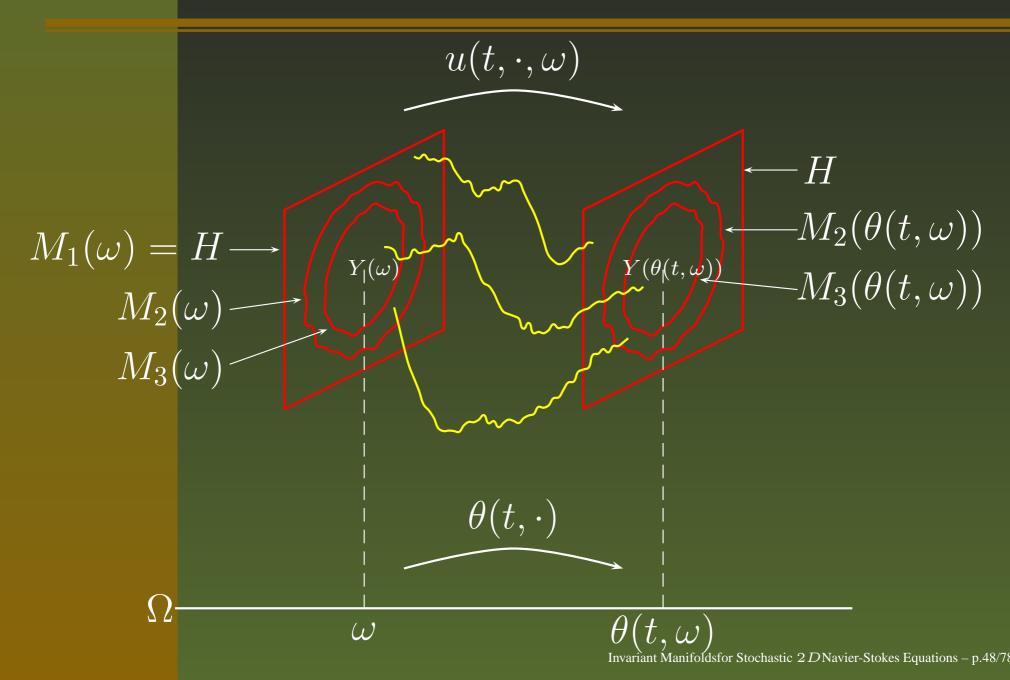
(iii) $M_{i+1}(\omega) \subseteq M_i(\omega)$.

(iii) $M_{i+1}(\omega) \subseteq M_i(\omega)$. (iv) For any $f \in M_i(\omega) \setminus M_{i+1}(\omega)$, $\overline{\lim_{t \to \infty}} \quad \frac{1}{t} \log |u(t, f, \omega) - Y(\theta(t, \omega))|_H \in (\lambda_{i+1}, \lambda_i]$.

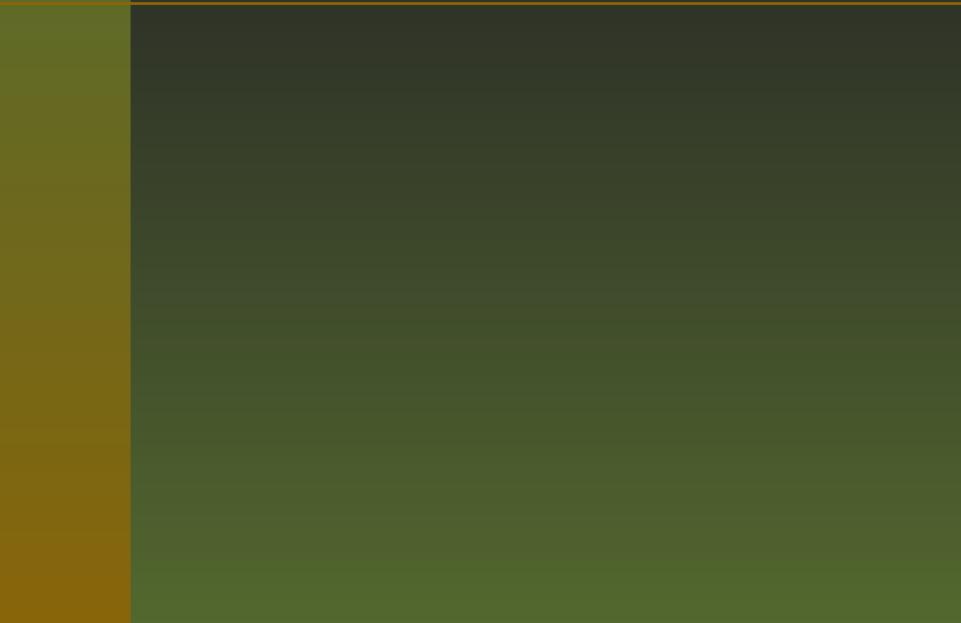
Global Invariant Flag



Global Invariant Flag



Burgers spde



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Similar (C^{∞}) dynamics holds for one-dimensional Burgers equation with affine white noise:

Burgers spde

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 $egin{aligned} du(t) &=
u \Delta u \, dt - u rac{\partial u}{\partial \xi} \, dt + \gamma u(t) \, dt + \sigma_0 \, dW_0(t) \ &+ \sigma u(t) \, dW(t), \, t > 0, \, \xi \in [0,1], \ u(t,0) &= u(t,1) = 0 \ ext{ for all } t > 0, \ u(0,\xi) &= f(\xi), \, \xi \in [0,1]. \end{aligned}$

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THANK YOU!